

Department of Mathematics

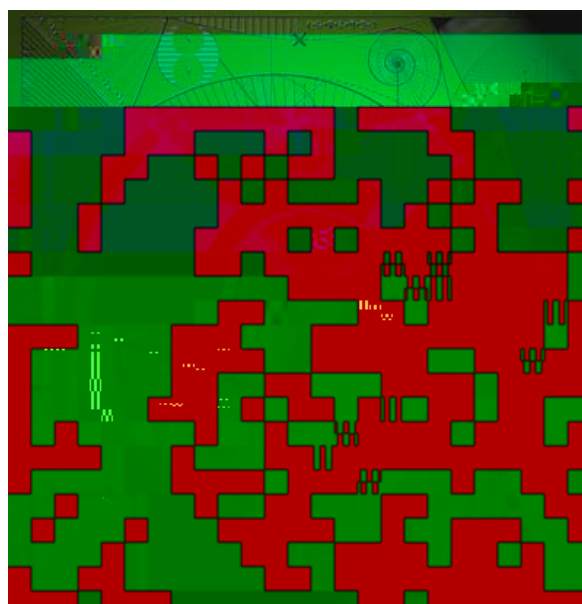
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State estimation using model order reduction for unstable systems

by

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State estimation using model order reduction for unstable systems

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T b  , a  a cc  a a  ca  , fl d fl .
F a  , d c a  ab  a , ca   a  fi d
b   b  a , a  a , a  . T fi d 
b   a a  a  a  a  b  a  b  c
d a ca   c  a  . U a    d a  b a a -
a Ga  -N d d   d c  a 
 a  ab  . I  a a d , d 
d a a  b  ba  d a c  d  d d 
d c d , ab   . T  a ca   ,

$a, \quad ca, \quad Da \, a \, a \quad a \quad c \quad a \quad fi \, d \quad b \quad a \, b$
 $c \quad b \quad b \quad a \quad da \, a \quad a \quad ca \quad d \quad . \, I$
 $a \quad c \quad -d \quad a \, a \, a \quad da \, a \, a \quad (4D-Va)$
 $a \quad b \quad d \, a \, a \quad a \quad a \quad a \quad b$

$$_x \quad (x) = f(x)^T f(x); \tag{1}$$

$f(x) \quad c \quad d \quad a \quad ca \quad d \quad T \quad ,$
 $d \, b \, a \quad a \quad a \quad a \quad Ga \quad -N \quad d,$
 $a \quad a \quad c \quad 4D-Va \quad [1, 2]. \, W \quad a \quad d$
 $a \quad c \quad a \quad d \quad Jac \, b \, a \quad , \quad c \quad f(x) \, a \, d$
 $c \quad Jac \, b \, a \quad , \quad a \quad ca \quad d \quad c \quad , \quad d$
 $a \quad a \quad a \quad d \quad (TLM). \, S \quad fica \quad ca$
 $d \, c \quad d \quad a \quad d \quad a \, d \quad ab \, b \, a$
 $I \quad ab \quad TLM \, a \quad d \quad a \quad ca \quad d$
 $a \quad a \quad ab \quad a \, fi \quad a \quad T \quad a \quad c$
 $b \, ab \quad a \quad a \quad ab \quad d \, b \quad d$
 $A \, c \quad d \, a \quad ac \quad d \, c \quad c \quad b$
 $(1) \quad a \quad a \quad TLM \, b \, a \quad a \quad d \quad d \, a \quad a \, a$
 $\quad . \, W \quad ad \quad a \quad a \quad a \quad ac \, ca \quad c$

$$\mathcal{S} : \begin{cases} \delta x_{i+1} &= M \delta x_i; \\ d_i &= H \delta x_i; \end{cases} \quad (6)$$
$$T : \mathbb{C} \rightarrow \mathbb{R}^{p-m}; \quad (7)$$

T (6) a ab, . . . a ,
a M a d a d c T b ab fi d
d a a (6) da ab d d c c
ab T d α-b d d ba c d ca a
c b d d [6] α-b ded, . . . a
a M ac a d a
ad α. F a ab S b fi d
c a α. T α-b d d ba c d ca c
a d a a c U a d V, c c a c d

$$\mathcal{S}: \begin{cases} \delta \hat{x}_{i+1} &= U^T M V \delta \hat{x}_i; \\ \hat{d}_i &= H V \delta \hat{x}_i; \end{cases} \quad (9)$$

$$\|T - \hat{T}\|_{h_{\infty, \alpha}} \leq 2(\sigma^l$$

$$F:\mathbb{C}\rightarrow\mathbb{R}^{m-p}$$

$\mathfrak{a}$ $\mathfrak{c}$ $\mathfrak{c}$ $\mathfrak{c}$ $\mathfrak{a}$ $\mathfrak{d}$
 $\mathfrak{ad}$ $\mathfrak{a}$ $\mathfrak{d}$, $\mathfrak{a}$ - $\mathfrak{b}$ $\mathfrak{d}$ $\mathfrak{d}$. $\mathfrak{T}$ $\mathfrak{ca}$
 $\sigma_{r+1}^{(\)};\cdots;\sigma_n^{(\)}$ $\mathfrak{a}$ $\mathfrak{Ha}$ $\mathfrak{a}$ $\mathfrak{a}$ - $\mathfrak{ca}$ $\mathfrak{d}$ $\mathcal{S}$,
 $\mathfrak{b}$ $\mathfrak{a}$ $\mathfrak{c}$

$$T=\frac{1}{\alpha}H(zI-\frac{1}{\alpha}M)^{-1}B_0^{\frac{1}{2}};$$

$\mathcal{G}a$ $\mathcal{N}$ $c d$. A a d c d a
 d a Ead d $x-z$ a d ba c c
 ab , c d a $c a$, a
 d d .

4.1. E e e a de g

T d a a $2D$ Ead d $[7]$ a d -
 c b d . T ba c a b a a d a , z ,
 a d a b d a da , $z = \pm \frac{1}{2}$.
 F $[8]$ a d a c a a
 c (QGPV) . T a a b ba
 b a c , $b = b(x; z; t)$, b da , $z = \pm \frac{1}{2}$, a $t = 0$. T a
 d ca c d ba c a , c -
 $, = (x; z; t)$, c a fi .

$$\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial z^2} = 0; \quad z \in [-\frac{1}{2}; \frac{1}{2}]; \quad x \in [0; X]; \quad (13)$$

b da c d a

$$\frac{\partial}{\partial z} = b; \quad z = \pm \frac{1}{2}; \quad x \in [0; X]; \quad (14)$$

P ba ba c a a ad c d a b ba c a fl
 a d c b d b $-d$ a QG d a c a :

$$\left(\frac{\partial}{\partial t} + z \frac{\partial}{\partial x} \right) b = \frac{\partial}{\partial x}; \quad z = \pm \frac{1}{2}; \quad x \in [0; X]; \quad (15)$$

T a a b da c d $x-d$ c a a b d c
 c a a a , t , a d , z , $b(0; z; t) = b(X; z; t)$ a d $(0; z; t) =$
 $(X; z; t)$. A $[8]$ d a x , z , a d t .
 I a d , Ead d d c d 11
 ca a c . T a 20 d a c b . T ad c a
 40 d d a a ad c c . W $[8]$, a
 d a . T b a a H c c a b a a
 a , a b a c .

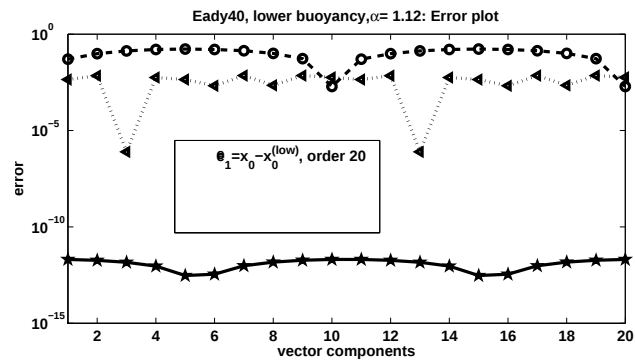
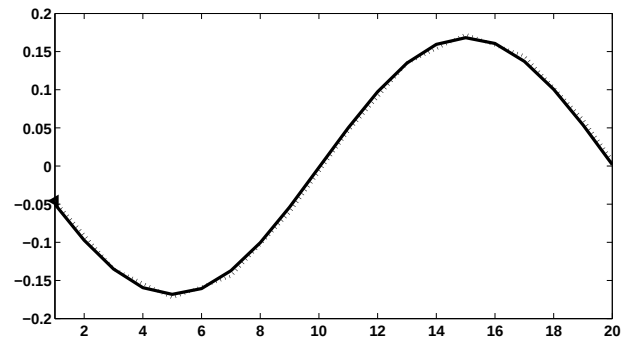
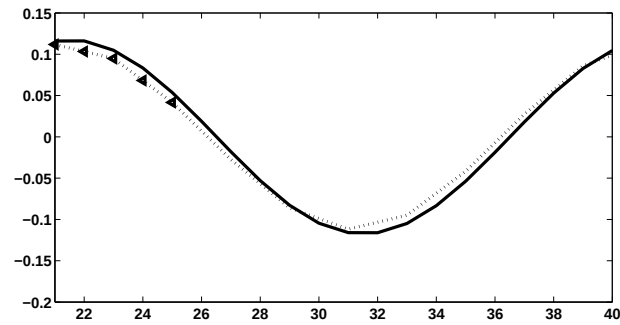


Figure 1: Comparison of low resolution (dotted line with triangles), standard balanced truncation (dashed line with circles), and high resolution (solid line with squares) methods. The x-axis represents the number of modes k (from 0 to 100), and the y-axis represents the error (from 0 to 1). The low resolution method shows a sharp increase in error after $k=20$. The standard balanced truncation method shows a more gradual increase in error. The high resolution method shows the lowest error across all k .

e

10 d , a d acc a .



(a) Solution on upper boundary

(b) Error on upper boundary

Figure 2: Comparison of low resolution (dotted line with triangles), standard balanced truncation (dashed line with circles) and α -bounded balanced truncation (solid line with stars) approximations to the buoyancy on the upper boundary

T a c . T b fi ca b d a b a c d c d d a W α -b d d d b a c fica a d a d a da d ba c d ca d F 3(a) a (c) F 3(b), 4(a) a d 4(b) a d ff d a a T α -b d d a a d a c a c F 3(b),

c $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$). I c $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ a $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$, $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ a da d ba $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ c d ca $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ d ($F^{\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}}$ 4(a),
c $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$) $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ ca ab $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$, a c $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ a $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ $\begin{smallmatrix} \bullet \\ \bullet \end{smallmatrix}$ d

b a , a , a a a , a
 d . I 4D-Va d ac d b
 a a a b c a d b a d a
 a d c b a , a I
 a a a ca , c b d a
 a a Ga-N c d . Eac a d
 c a a a a b b c a d a
 a a d (TLM). T TLM d d c d, a a
 a d a b ab a fi d . T a c a
 d d a d, a a a d ab.
 U a TLM a a d b a d a a a
 I a a d a d d c d , α-
 b d d ba c d ca a b d b a b a a-
 ab TLM Ga-N c d . T d
 d c c c a d a a TLM
 ca c a I ca b a d d d
 b , ab , d c , a
 ba b d ca b d.
 T d d d c a a , a d
 d d d a , ab, a a , H ,
 b a d ac ca b
 K b ac c fi d c
 W a c a d α-b d d ba c d ca d
 a da d ba c d ca a ac , ab a d
 a a ca a 2-d a
 Ead d T Ead d a d , ba c c ab ,
 c d a c a , a d d
 I ca d a ca α-
 b d d a a d . I ca d a b a ,
 d d . T d a a b a c
 a d b da a d d ab, d d . I
 a d , a d b a a d
 a d a a a c

T a d a b NERC Na a C , Ea
 Ob a .

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a a a da a a . I J, N ca M d F d
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d d . I J N M d F d 2008;56:1367-73.
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